

Linear axes & linear axis systems

Linear tables HT-L

9. Linear tables HT-L

9.1 Properties of linear tables HT-S with linear motor

The HIWIN linear axes with linear motor are flexible positioning modules with integrated HIWIN double guide. They are especially suitable for precise positioning at high speed and with great dynamics.

Cleanroom-compatible linear motor axes HT-L up to ISO class 4 are available on request.

FUNCTIONAL
SAFETY

IPA
CLEAN ROOM
ISO 4



Linear guideway

A high-quality HIWIN double guide safely transfers forces and torques from the carriage to the axis profile. Four blocks are used per carriage, which are guided on a two parallel, high-precision profile rails. The SynchMotion™ technology with ball chain also ensures good synchronisation and smooth running in the HT150L, HT200L and HT250L sizes.



Electric interface

The quick-release connectors allow motor and encoder cables to be connected quickly and easily to the side of the carriage without tools. Depending on the installation situation and the desired cable routing, two different orientations of the connector are available as options.



Linear motor

The integrated HIWIN linear motors ensure dynamic and precise positioning. Two motor sizes are available for each size in order to optimally meet the requirements for the required feed force.



Energy chain

Generously dimensioned energy chains provide space for safely carrying the supply lines. They are extremely compact and save space when attached to the axis. For details on the orientation of the energy chain, see section [22.4 from page 188](#).



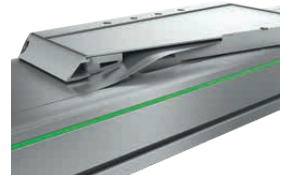
Carriage

The carriages have additional bore holes on each mounting hole to ensure ideal, reproducible alignment of the adjacent construction. You will find the matching centring sleeves in the accessories on [Page 192](#). A grease nipple is provided on the carriage for each lubrication point for convenient maintenance of the linear axis.



Cover strip

The steel cover strip prevents dirt and dust from entering the axis interior. In addition, the cover strip allows the axes to be used in areas with coarse, sharp-edged or hot foreign bodies. The magnetic strips integrated in the axis profile hold the belt securely in position and increase the sealing effect.

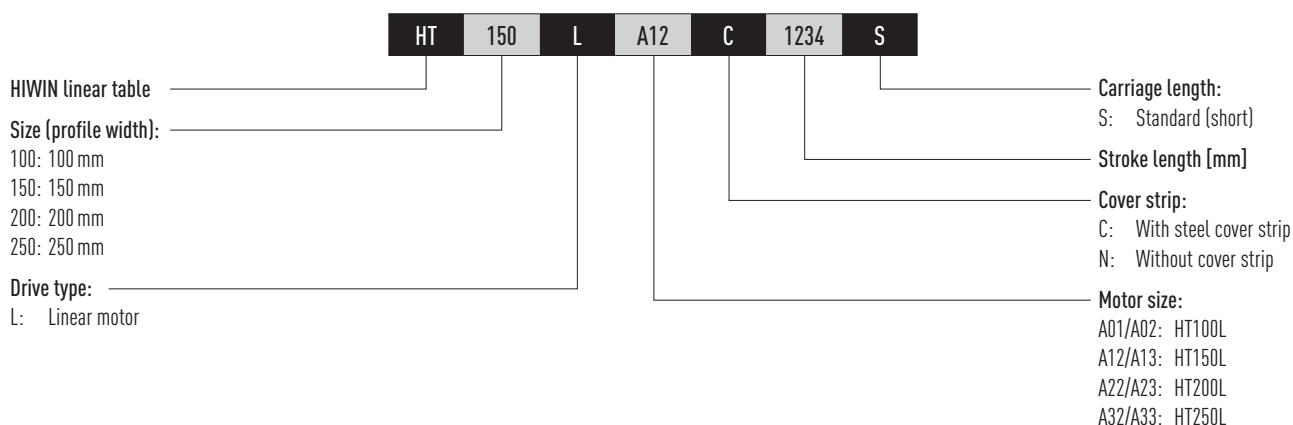


Positioning measuring systems

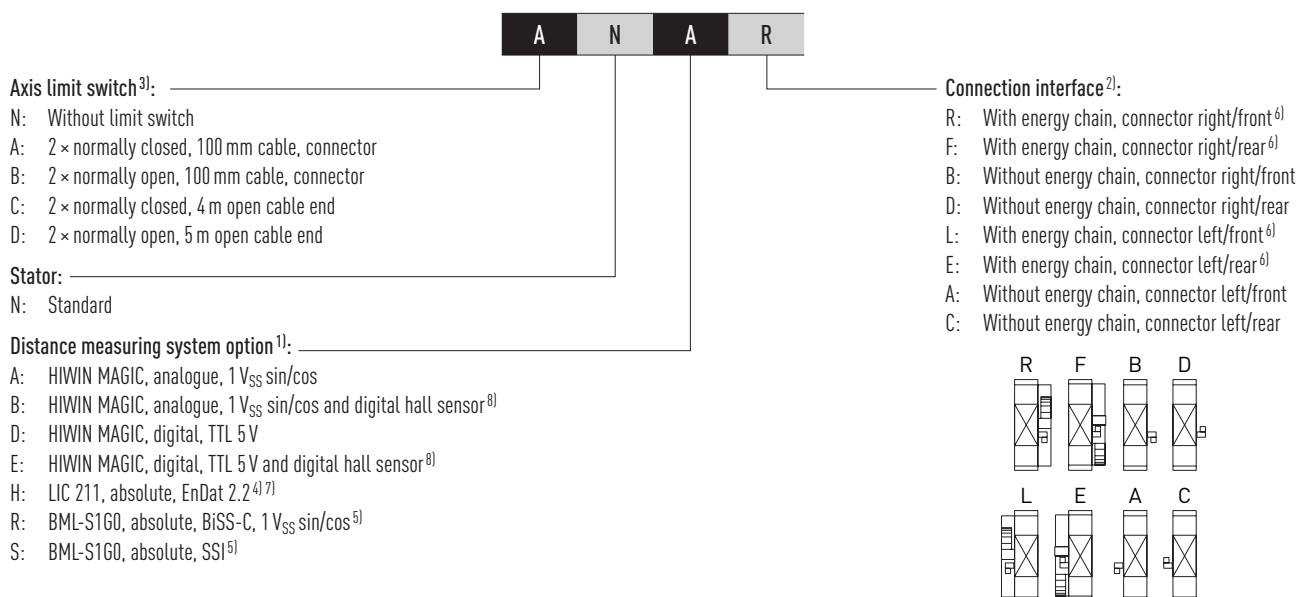
The distance measuring system is integrated into the inside of the axis to save space and determines the repeatability. Different measuring systems are available depending on the requirements for measuring method, interface and resolution. You can find more information on [Page 156](#). Optionally also with functional safety encoder.



9.2 Order code for linear tables HT-L



Continuation, order code for linear tables HT-L



¹⁾ More detailed information in chapter 21 from page 156 or in the "HIWIN MAGIC Distance Measuring Systems" assembly instructions".

²⁾ Details on connector orientation and position of the energy chain in section 22.4 from page 188.

³⁾ Additional reference switches on request.

⁴⁾ Limitations of the maximum stroke possible, see Table 21.1 on page 156.

⁵⁾ The distance measuring system has a safety-related, analogue, incremental real-time signal.

⁶⁾ Max. possible stroke: 5,000 mm.

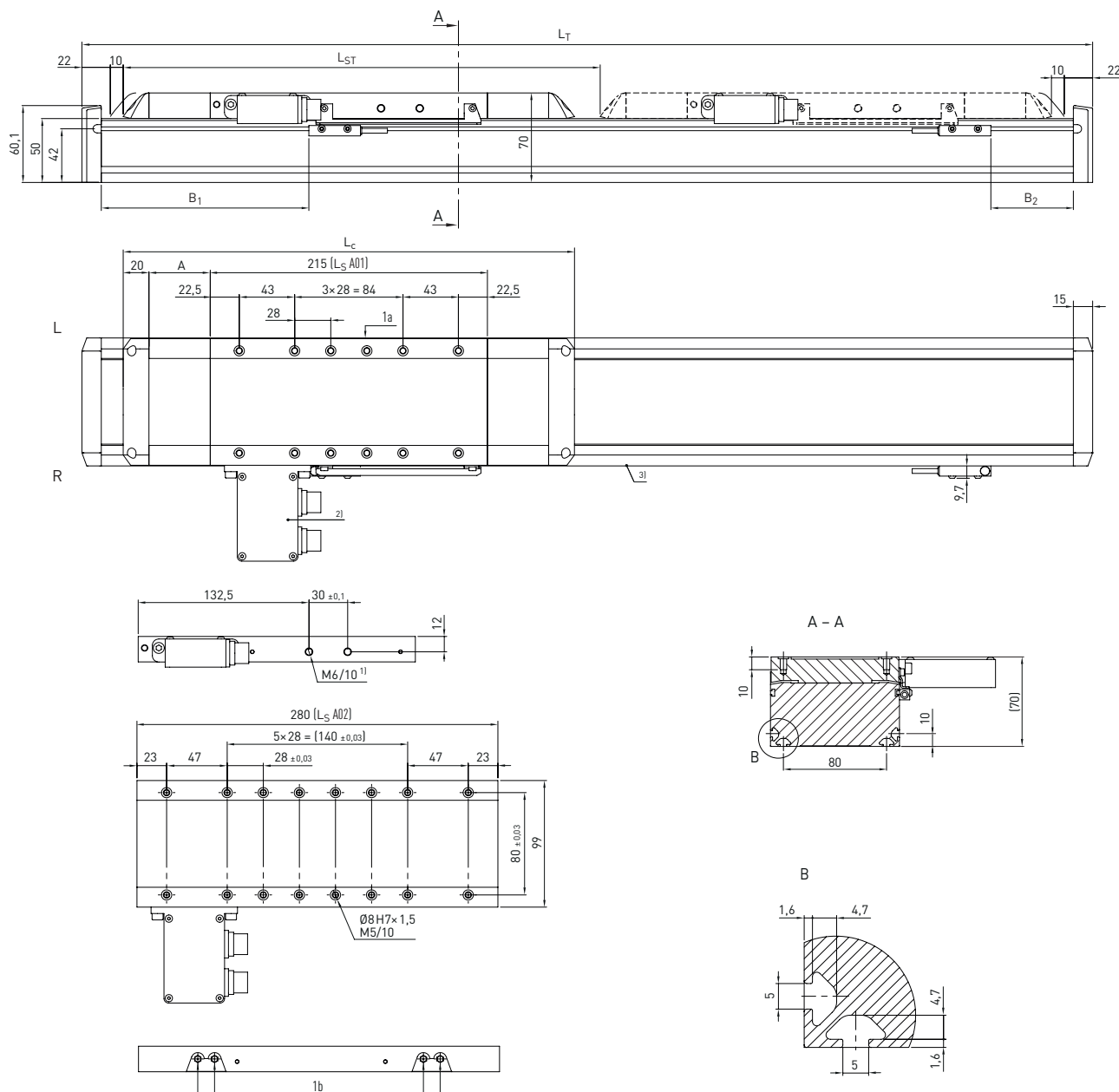
⁷⁾ If the installation position is horizontal, the axis must be arranged so that the distance measuring system is at the top.

⁸⁾ Option not available for HT100L.

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9.3 Dimensions and specifications of HT100L



L_S Carriage plate
 L Left
 R Right
 $1a + 1b$ Block lubrication connectors

¹⁾ Omitted for variant with energy chain ²⁾ Drive interface shown: Option "D"; for other series, see section 22.4 from page 188

³⁾ Internal measuring system always on the right side of the axis. The positive direction of travel depends on the selected measuring system, see section 21.2 from page 158

Table 9.1 HT100L dimensions				
	Variant without cover		Variant with cover	
Motor size	A01	A02	A01	A02
Total carriage length L_C [mm]	255	320	350	415
Cover strip deflection A [mm]	—	—	47.5	47.5
Switch distance B_1 [mm]	113.5	113.5	161	161
Switch distance B_2 [mm]	36.5	101.5	84	149
Max. stroke length L_{ST} [mm]	5,511	5,446	5,416	5,351
Total length L_T [mm]	$L_T = L_{ST} + 319$	$L_T = L_{ST} + 384$	$L_T = L_{ST} + 414$	$L_T = L_{ST} + 479$

Table 9.2 Load data

	Permissible load data		Theoretical load data	
Lifetime reference value	10,000 km		100 km	
Motor size	A01	A02	A01	A02
$F_{y\text{dynmax}}^{1)}$ [N]	1,101	860	8,096	8,096
$F_{z\text{dynmax}}^{1)}$ [N]	1,101	860	8,096	8,096
$M_{x\text{dynmax}}$ [Nm]	35	27	255	255
$M_{y\text{dynmax}}$ [Nm]	96	103	704	967
$M_{z\text{dynmax}}$ [Nm]	96	103	704	967
Load distance z [mm]	53.5	53.5	53.5	53.5

¹⁾ Force must only act free of torque

Table 9.3 General technical data

Repeatability ²⁾ [mm]	± 0.005
Max. speed [m/s]	5
Typical load capacity [kg]	20
Maximum total length ^{2) 3)} [mm]	5,830
Flatness ¹⁾ [mm/300 mm]	± 0.03
Straightness ¹⁾ [mm/300 mm]	± 0.03
Area moment of inertia of profile cross section I_x [mm ⁴]	282,903
Area moment of inertia of profile cross section I_y [mm ⁴]	1,541,419

¹⁾ Values apply with specified screw-on surface or mounting plate

²⁾ Depending on distance measuring system (chapter 21) and energy chain (section 22.4)

³⁾ Long axes on request

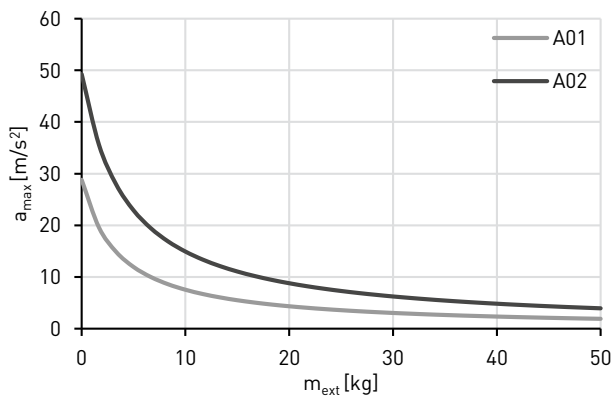
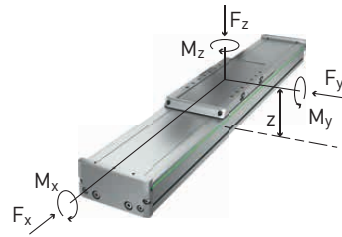

 Fig. 9.1 Max. acceleration a_{max} as a function of the external payload m_{ext}


Table 9.4 Guide

Type of carriage	MGN09H × 4
Static load rating C_0 [N]	4,020 × 4
Dynamic load rating C_{dyn} 50 km [N]	2,550 × 4

Table 9.5 Drive

Motor size	A01	A02
Motor type	LMSA01	LMSA02
Continuous force [N]	52	104
Peak force [N]	112	224
Max. acceleration [m/s ²]	30	50

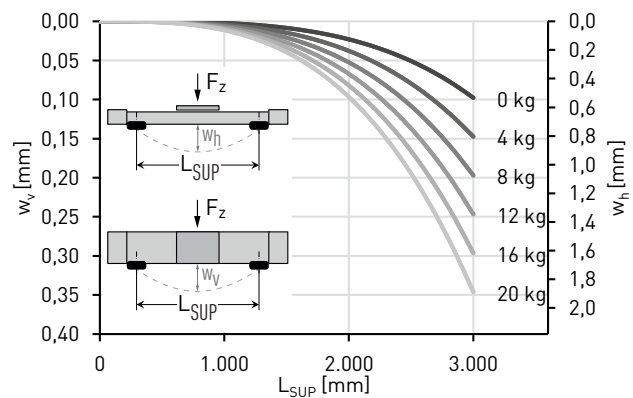

 Fig. 9.2 Deflection w over unsupported axis length L_{SUP} under load capacity F_z

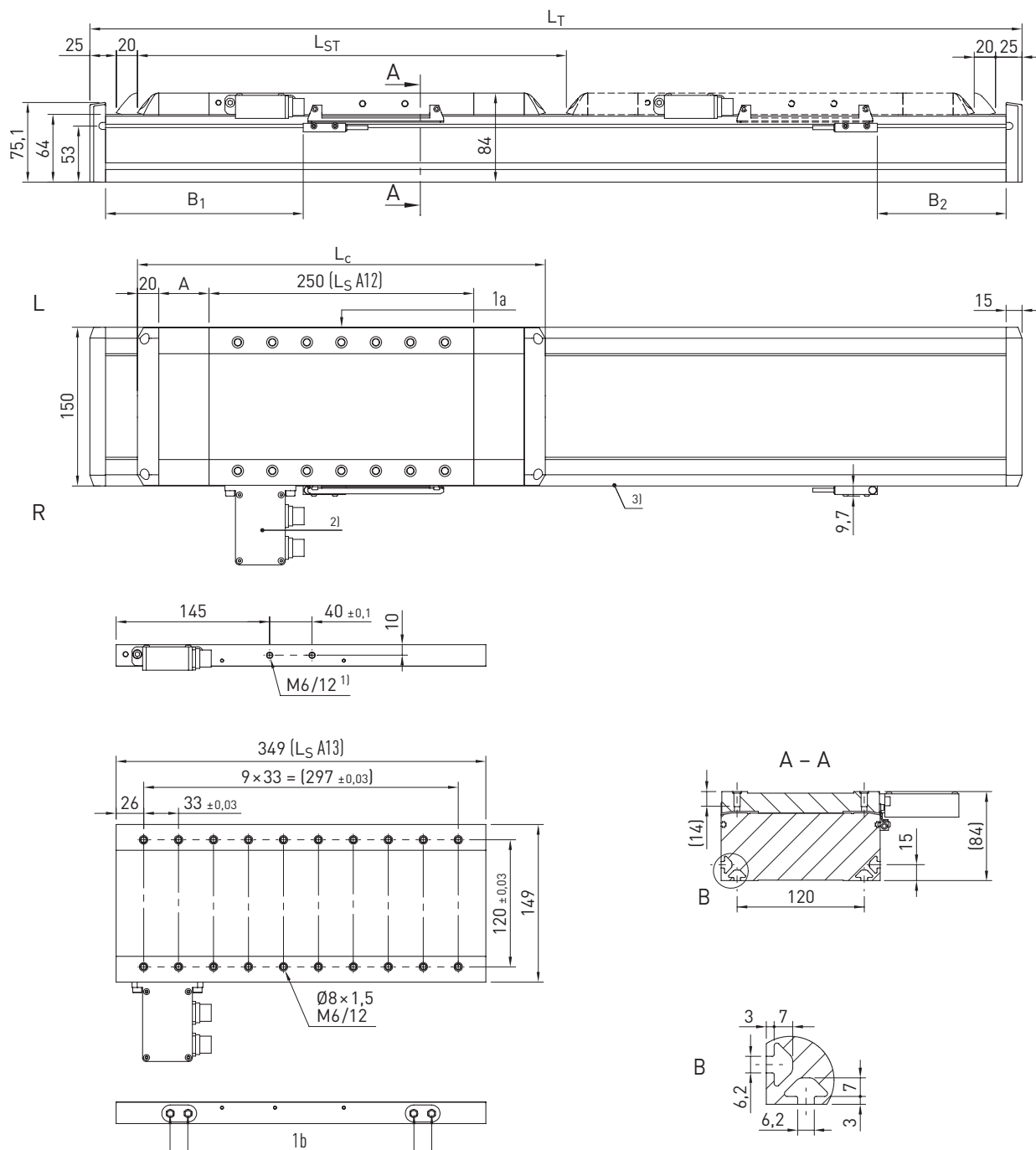
Table 9.6 Mechanical properties

	Variant without cover		Variant with cover	
Motor size	A01	A02	A01	A02
Mass of the carriage [kg]	1.97	2.78	2.26	3.06
Mass at 0-stroke [kg]	4.15	5.42	5.02	6.30
Mass per 1 m stroke [kg/m]	6.45		6.61	
Breakaway force F_l [N]	5.00		10.00	

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9.4 Dimensions and specifications of HT150L



L_S Carriage plate
L Left
R Right
1a + 1b Block lubrication connectors

¹⁾ Does not apply to version with energy chain ²⁾ Drive interface shown: Option "D"; for other versions, see section 22.4 from page 188

³⁾ Internal measuring system always on the right side of the axis. The positive direction of travel depends on the selected measuring system, see section 21.2 from page 158

Table 9.7 HT150L dimensions				
	Variant without cover		Variant with cover	
Motor size	A12	A13	A12	A13
Total carriage length L _c [mm]	290	389	385	484
Cover strip deflection A [mm]	—	—	48	48
Switch distance B ₁ [mm]	138	138	185.5	185.5
Switch distance B ₂ [mm]	73	172	121	220
Max. stroke length L _{ST} [mm]	5,450	5,351	5,355	5,256
Total length L _T [mm]	L _T = L _{ST} + 380	L _T = L _{ST} + 479	L _T = L _{ST} + 475	L _T = L _{ST} + 574

Table 9.8 Load data

	Permissible load data		Theoretical load data	
Lifetime reference value	20,000 km		100 km	
Motor size	A12	A13	A12	A13
$F_{y\text{dynmax}}^{1)}$ [N]	3,350	3,350	39,780	39,780
$F_{z\text{dynmax}}^{1)}$ [N]	4,270	3,789	39,780	39,780
$M_{x\text{dynmax}}$ [Nm]	201	178	1,870	1,870
$M_{y\text{dynmax}}$ [Nm]	414	555	3,859	5,828
$M_{z\text{dynmax}}$ [Nm]	325	491	3,859	5,828
Load distance z [mm]	51.4	51.4	51.4	51.4

¹⁾ Force must only act free of torque

Table 9.9 General technical data

Repeatability ²⁾ [mm]	± 0.005
Max. speed [m/s]	5
Typical load capacity [kg]	80
Maximum total length ^{2) 3)} [mm]	5,830
Flatness ¹⁾ [mm/300 mm]	± 0.03
Straightness ¹⁾ [mm/300 mm]	± 0.03
Area moment of inertia of profile cross section I_x [mm ⁴]	907,754
Area moment of inertia of profile cross section I_y [mm ⁴]	7,417,610

¹⁾ Values apply with correspondingly specified screw-on surface or mounting plate

²⁾ Depending on distance measuring system (chapter 21) and energy chain (section 22.4)

³⁾ Long axes on request

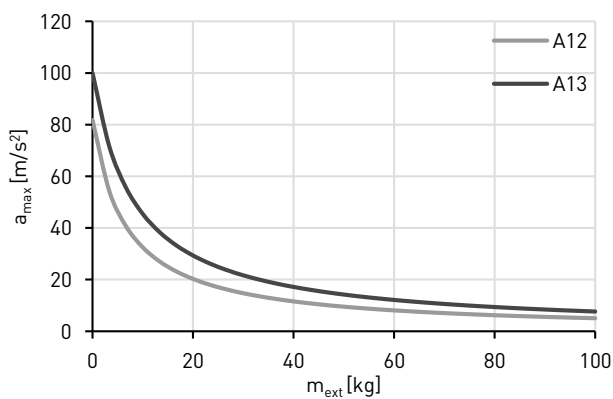


Fig. 9.3 Max. acceleration a_{max} as a function of the external payload m_{ext}

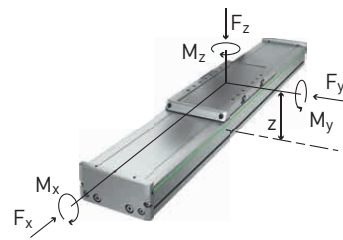


Table 9.10 Guide

Type of carriage	QEH15CA × 4
Static load rating C_0 [N]	15,280 × 4
Dynamic load rating C_{dyn} 50 km [N]	12,530 × 4

Table 9.11 Drive

Motor size	A12	A13
Motor type	LMSA12	LMSA13
Continuous force [N]	205	308
Peak force [N]	579	868
Max. acceleration [m/s ²]	60	80

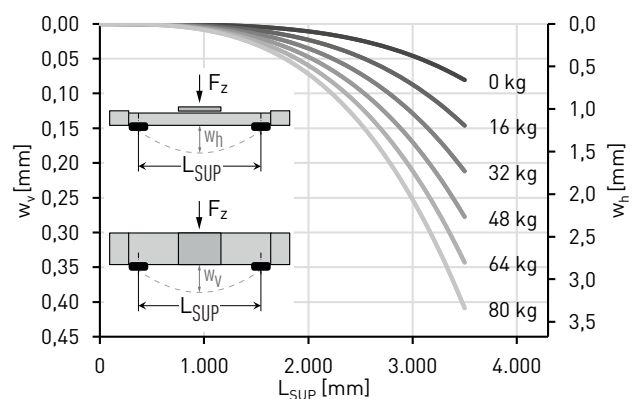


Fig. 9.4 Deflection w over unsupported axis length L_{SUP} under load capacity F_z

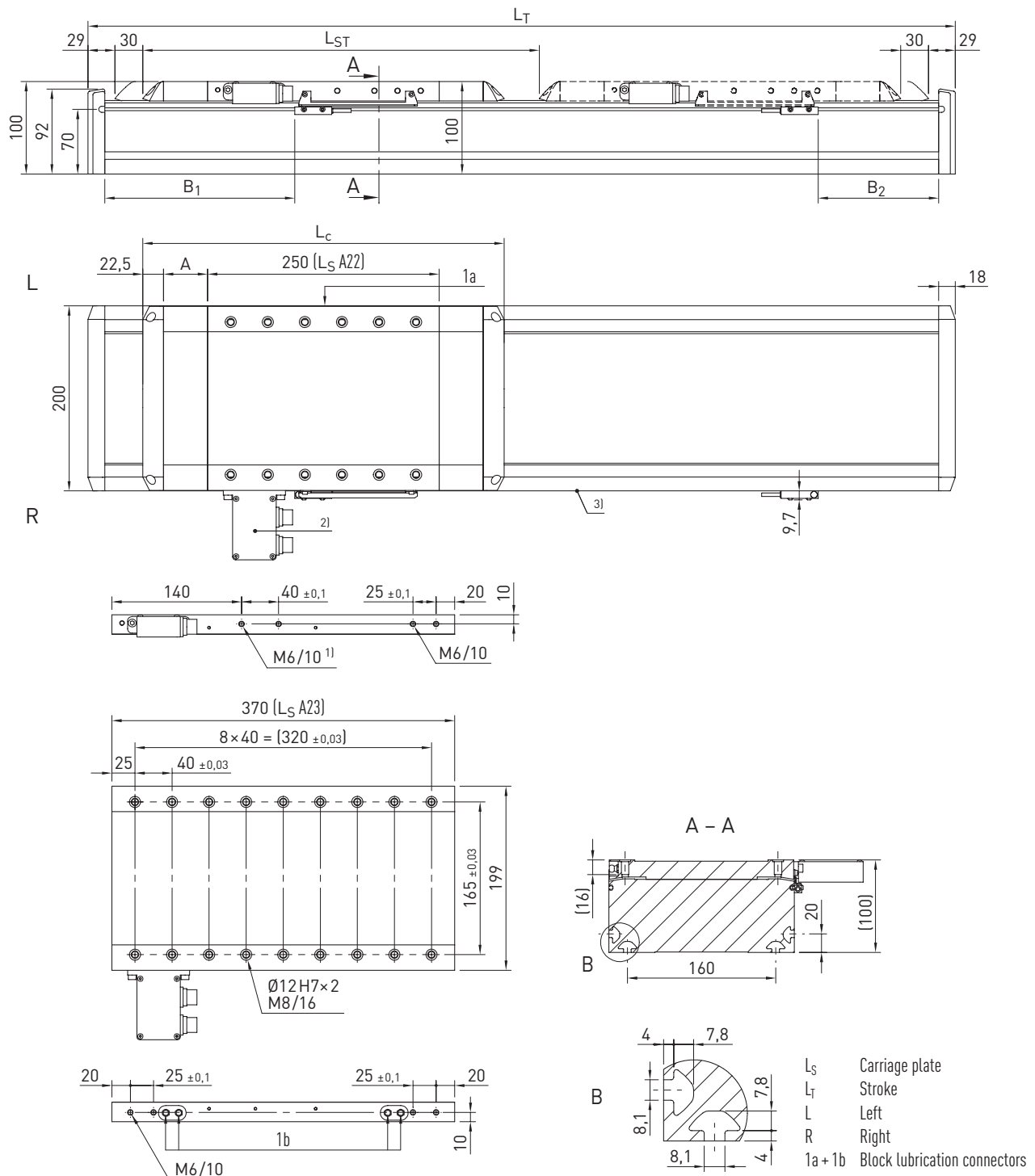
Table 9.12 Mechanical properties

	Variant without cover		Variant with cover	
Motor size	A12	A13	A12	A13
Mass of the carriage [kg]	4.24	5.87	4.72	6.35
Mass at 0-stroke [kg]	9.76	12.75	11.53	14.55
Mass per 1 m stroke [kg/m]	13.59		13.88	
Breakaway force F_L [N]	12.00		40.00	

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9.5 Dimensions and specifications of HT200L



¹⁾ Omitted for variant with energy chain ²⁾ Drive interface shown: Option "D"; for other series, see section 22.4 from page 188

³⁾ Internal measuring system always on the right side of the axis. The positive direction of travel depends on the selected measuring system, see section 21.2 from page 158

Table 9.13 HT200L dimensions

	Variant without cover		Variant with cover	
	A22	A23	A22	A23
Total carriage length L_C [mm]	295	415	390	510
Cover strip deflection A [mm]	—	—	48	48
Switch distance B_1 [mm]	156.5	156.5	204	204
Switch distance B_2 [mm]	81.5	201.5	129	249
Max. stroke length L_{ST} [mm]	5,423	5,303	5,328	5,208
Total length L_T [mm]	$L_T = L_{ST} + 413$	$L_T = L_{ST} + 533$	$L_T = L_{ST} + 508$	$L_T = L_{ST} + 628$

Table 9.14 Load data

	Permissible load data		Theoretical load data	
Lifetime reference value	20,000 km		100 km	
Motor size	A22	A23	A22	A23
$F_{y\text{dynmax}}^{1)}$ [N]	7,800	7,800	95,244	95,244
$F_{z\text{dynmax}}^{1)}$ [N]	10,602	9,640	95,244	95,244
$M_{x\text{dynmax}}$ [Nm]	721	656	6,477	6,477
$M_{y\text{dynmax}}$ [Nm]	1,007	1,494	9,048	14,763
$M_{z\text{dynmax}}$ [Nm]	741	1,209	9,048	14,763
Load distance z [mm]	58.5	58.5	58.5	58.5

¹⁾ Force must only act free of torque

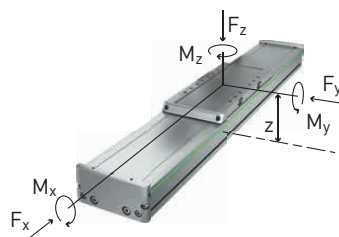


Table 9.15 General technical data

Repeatability [mm] ²⁾	± 0.005
Max. speed [m/s]	5
Typical load capacity [kg]	150
Maximum total length ^{2) 3)} [mm]	5,836
Flatness ¹⁾ [mm/300 mm]	± 0.03
Straightness ¹⁾ [mm/300 mm]	± 0.03
Area moment of inertia of profile cross section I_x [mm ⁴]	2,071,928
Area moment of inertia of profile cross section I_y [mm ⁴]	19,658,810

¹⁾ Values apply with specified screw-on surface or mounting plate

²⁾ Depending on distance measuring system (chapter 21) and energy chain (section 22.4)

³⁾ Long axes on request

Table 9.16 Guide

Type of carriage	QHH20CA × 4
Static load rating C_0 [N]	33,860 × 4
Dynamic load rating C_{dyn} 50 km [N]	30,000 × 4

Table 9.17 Drive

Motor size	A22	A23
Motor type	LMSA22	LMSA23
Continuous force [N]	362	544
Peak force [N]	1,023	1,535
Max. acceleration [m/s ²]	60	80

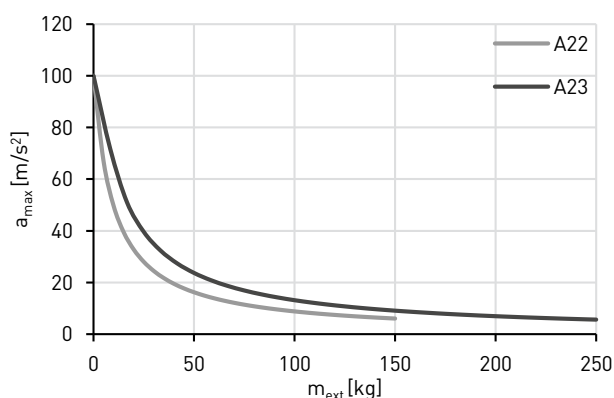


Fig. 9.5 Max. acceleration a_{max} as a function of the external payload m_{ext}

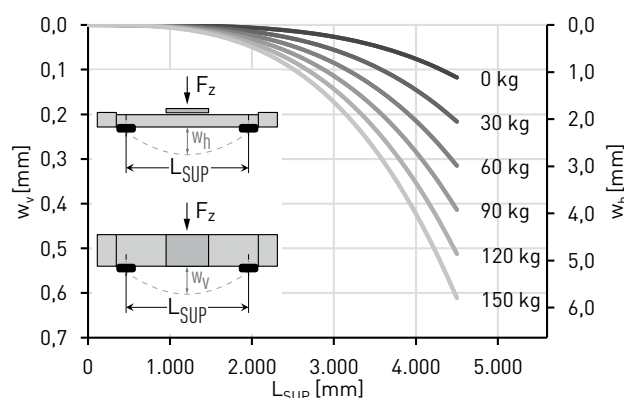


Fig. 9.6 Deflection w over unsupported axis length L_{SUP} under load capacity F_z

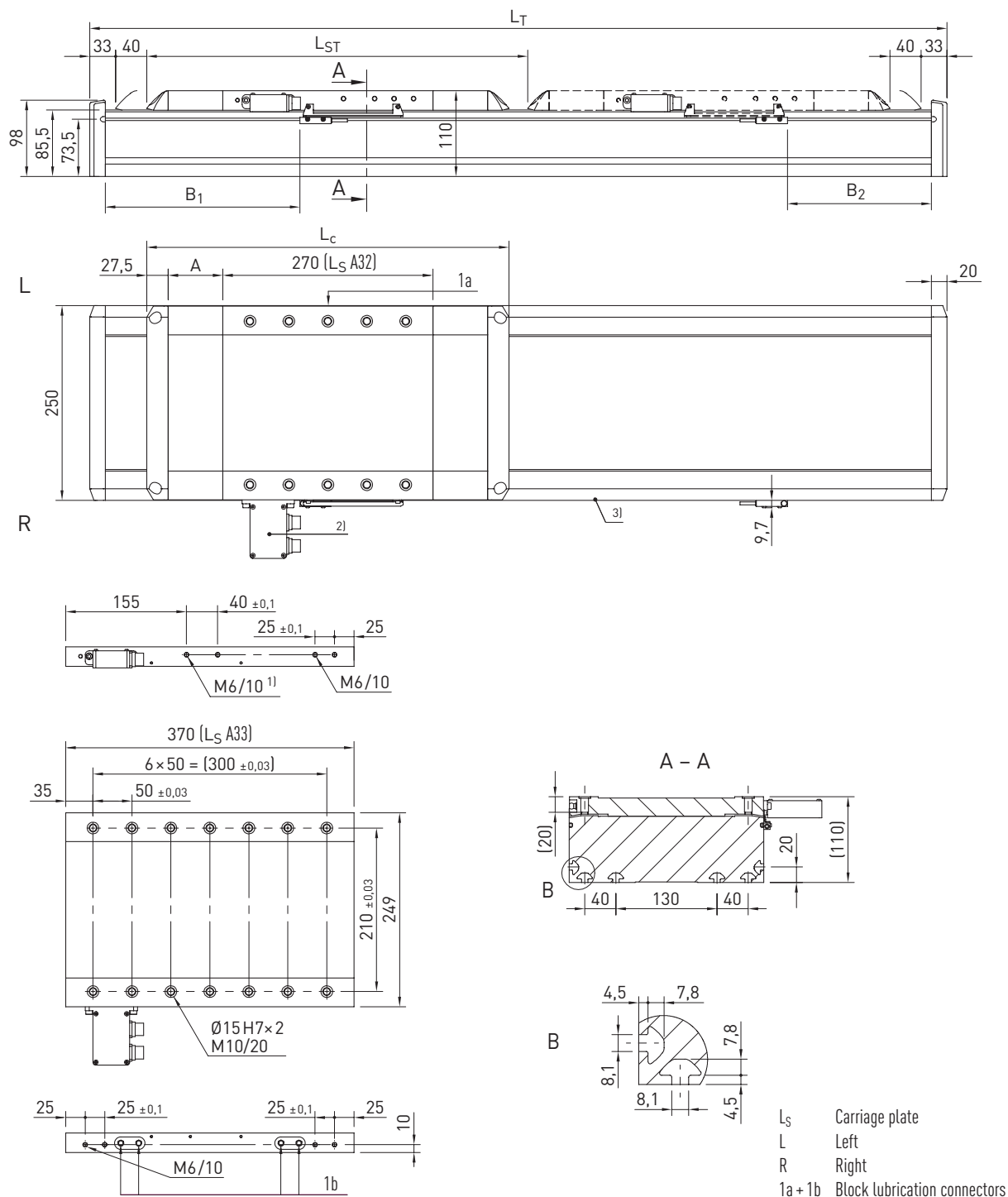
Table 9.18 Mechanical properties

	Variant without cover		Variant with cover	
Motor size	A22	A23	A22	A23
Mass of the carriage [kg]	6.69	9.46	7.28	10.14
Mass at 0-stroke [kg]	16.42	21.82	19.06	24.59
Mass per 1 m stroke [kg/m]	22.21		22.69	
Breakaway force F_l [N]	15.00		60.00	

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Linear tables HT-L

9.6 Dimensions and specifications of HT250L



¹⁾ Omitted for variant with energy chain ²⁾ Drive interface shown: Option "D"; for other series, see section 22.4 from page 188

³⁾ Internal measuring system always on the right side of the axis. The positive direction of travel depends on the selected measuring system, see section 21.2 from page 158

Table 9.19 HT250L dimensions

	Variant without cover		Variant with cover	
	A32	A33	A32	A33
Total carriage length L_C [mm]	325	425	465	565
Cover strip deflection A [mm]	—	—	70	70
Switch distance B_1 [mm]	178.5	178.5	248.5	248.5
Switch distance B_2 [mm]	113.5	213.5	183.5	283.5
Max. stroke length L_{ST} [mm]	5,469	5,369	5,329	5,229
Total length L_T [mm]	$L_T = L_{ST} + 471$	$L_T = L_{ST} + 571$	$L_T = L_{ST} + 611$	$L_T = L_{ST} + 711$

Table 9.20 Load data

	Permissible load data		Theoretical load data	
Lifetime reference value	20,000 km		100 km	
Motor size	A32	A33	A32	A33
$F_{y\text{dynmax}}^{1)}$ [N]	11,600	11,600	133,024	133,024
$F_{z\text{dynmax}}^{1)}$ [N]	14,610	13,165	133,024	133,024
$M_{x\text{dynmax}}$ [Nm]	1,249	1,126	11,374	11,374
$M_{y\text{dynmax}}$ [Nm]	1,424	1,942	12,970	19,621
$M_{z\text{dynmax}}$ [Nm]	1,131	1,711	12,970	19,621
Load distance z [mm]	68	68	68	68

¹⁾ Force must only act free of torque

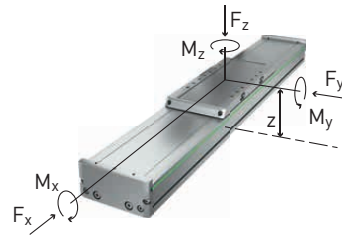


Table 9.21 General technical data

Repeatability ²⁾ [mm]	± 0.005
Max. speed [m/s]	4.5
Typical load capacity [kg]	250
Maximum total length ^{2) 3)} [mm]	5,940
Flatness ¹⁾ [mm/300 mm]	± 0.03
Straightness ¹⁾ [mm/300 mm]	± 0.03
Area moment of inertia of profile cross section I_x [mm ⁴]	3,265,771
Area moment of inertia of profile cross section I_y [mm ⁴]	39,262,043

¹⁾ Values apply with correspondingly specified screw-on surface or mounting plate

²⁾ Depending on distance measuring system (chapter 21) and energy chain (section 22.4)

³⁾ Long axes on request

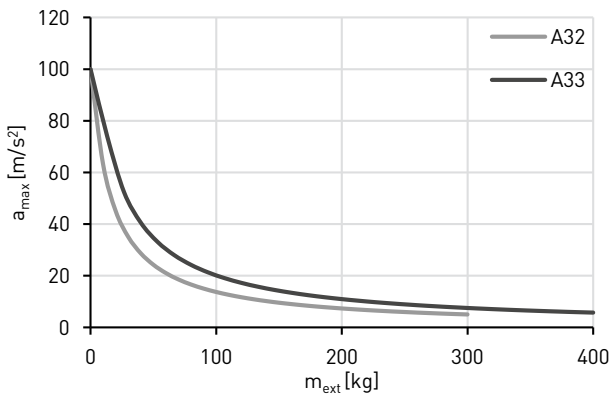


Fig. 9.7 Max. acceleration a_{max} as a function of the external payload m_{ext}

Table 9.22 Guide

Type of carriage	QHH25CA × 4
Static load rating C_0 [N]	48,750 × 4
Dynamic load rating C_{dyn} 50 km [N]	41,900 × 4

Table 9.23 Drive

Motor size	A32	A33
Motor type	LMSA32	LMSA33
Continuous force [N]	583	875
Peak force [N]	1,646	2,469
Max. acceleration [m/s ²]	60	80

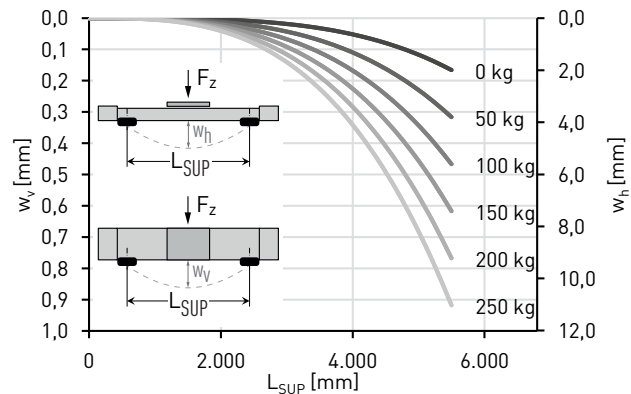


Fig. 9.8 Deflection w over unsupported axis length L_{SUP} under load capacity F_z

Table 9.24 Mechanical properties

	Variant without cover		Variant with cover	
Motor size	A32	A33	A32	A33
Mass of the carriage [kg]	11.74	15.63	12.85	17.04
Mass at 0-stroke [kg]	26.72	33.72	31.83	39.18
Mass per 1 m stroke [kg/m]	30.82		31.41	
Breakaway force F_l [N]	20.00		70.00	